

SOSflow: A Scalable Observation System for Introspection and In Situ Analytics

Efficiently observing and interacting with complex scientific workflows at scale presents unique challenges. **SOSflow helps meet them.**

- behavior

- insights

- SOSflow written in C99 for highperformance w/small footprint
- Several communication backends are supported, including EVPath, MPI, sockets, and ZeroMQ
- Asynchronous design focuses on minimizing overhead and time spent in API calls within client applications
- Flexible, programmable interface
- Provides a distributed key/value store with full SQL query support
- Offers a low-latency value cache with adjustable depth
- Highly-configurable daemons Integrated support for UID/GID
- authentication (Munge)

Design and API

"Hello, SOS" w/C:

- int main(int argc, char **argv) {
- // Initialize the client, registering it with the SOS runtime. // In an MPI application, this is usually called immediately // after the MPI_Init(...) call. SOS_runtime *sos = NULL;
- SOS_init(&argc, &argv, &sos, SOS_ROLE_CLIENT, SOS_RECIEVES_NO_FEEDBACK, NULL);
- SOS_pub *pub = NULL; SOS_pub_create(sos, &pub, "demo", SOS NATURE CREATE OUTPUT);

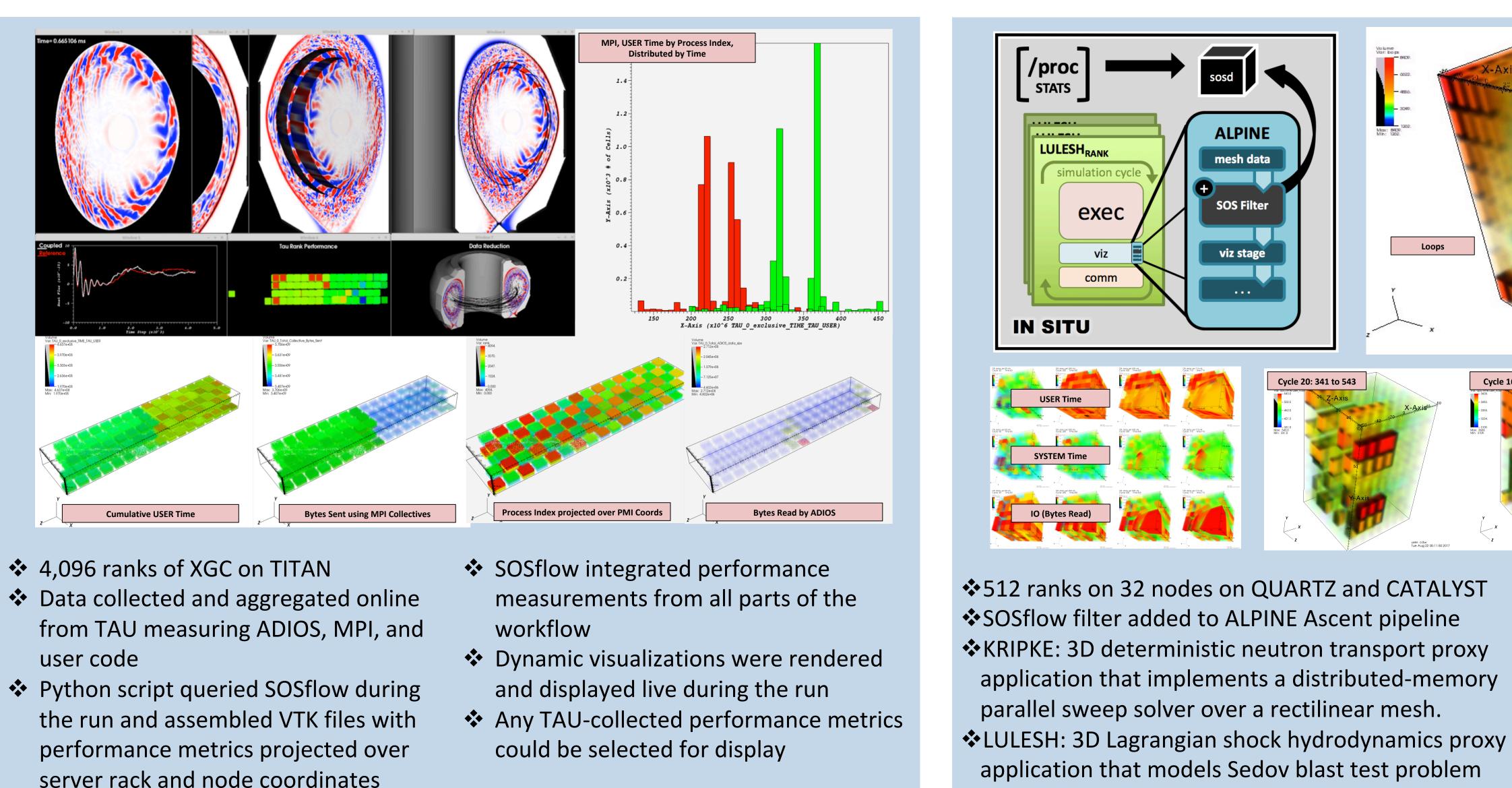
int someInteger = 256; SOS_pack(pub, "examplevalue", SOS_VAL_TYPE_INT, &someInteger);

SOS_announce(pub); SOS_publish(pub);

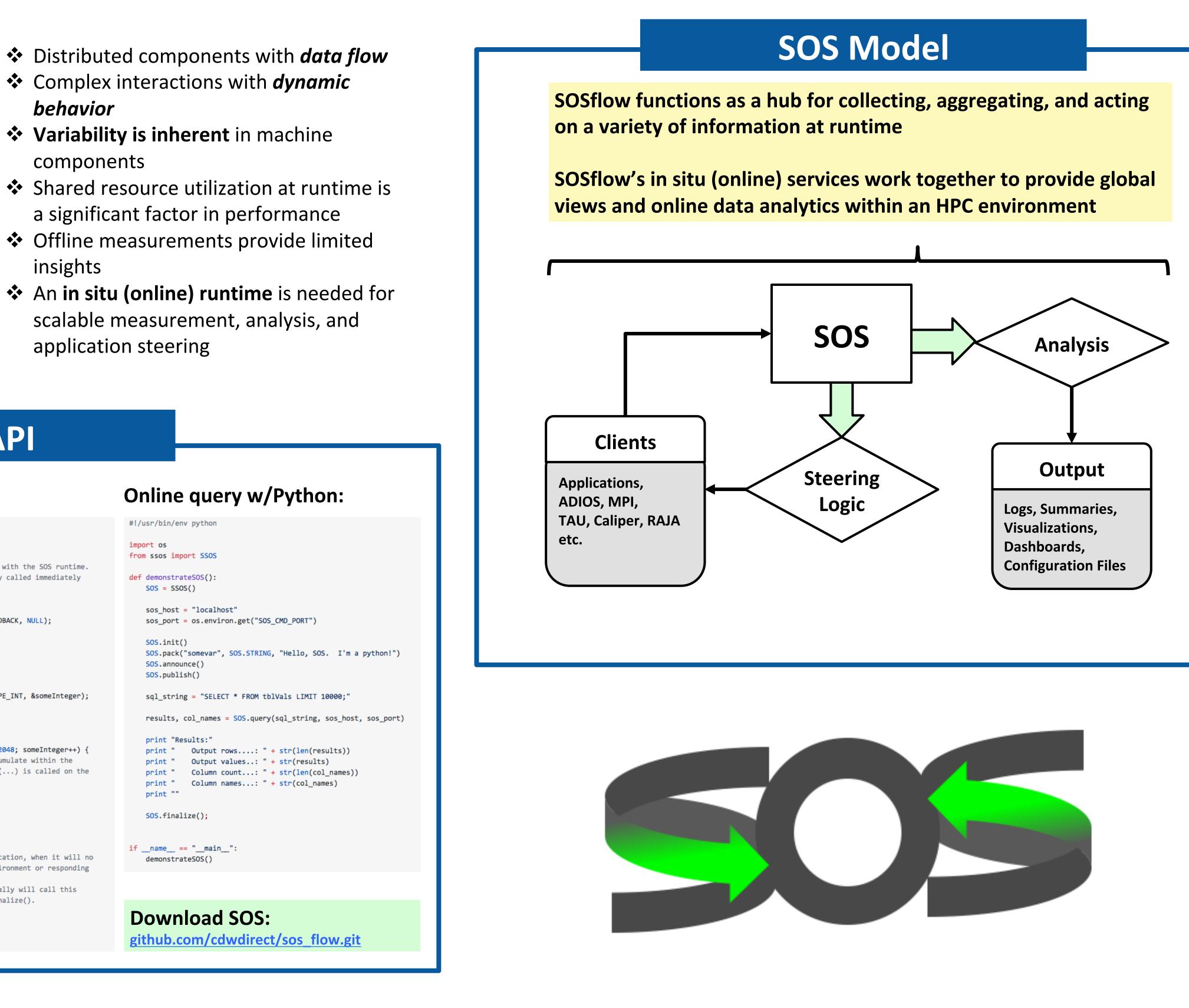
- (someInteger = 1024; someInteger <= 2048; someInteger++)</pre> // All these pack'ed values will accumulate within the // client until the next SOS_publish(...) is called on the // publication handle SOS_pack(pub, "examplevalue",
- SOS_VAL_TYPE_INT, &someInteger);

SOS_publish(pub)

- // This is called at the end of an application, when it will no iting to the SOS environment or respondir // In an MPI application, the client usually will call this // immediately before the call to MPI_finalize().
- SOS_finalize(sos); return 0;



- server rack and node coordinates



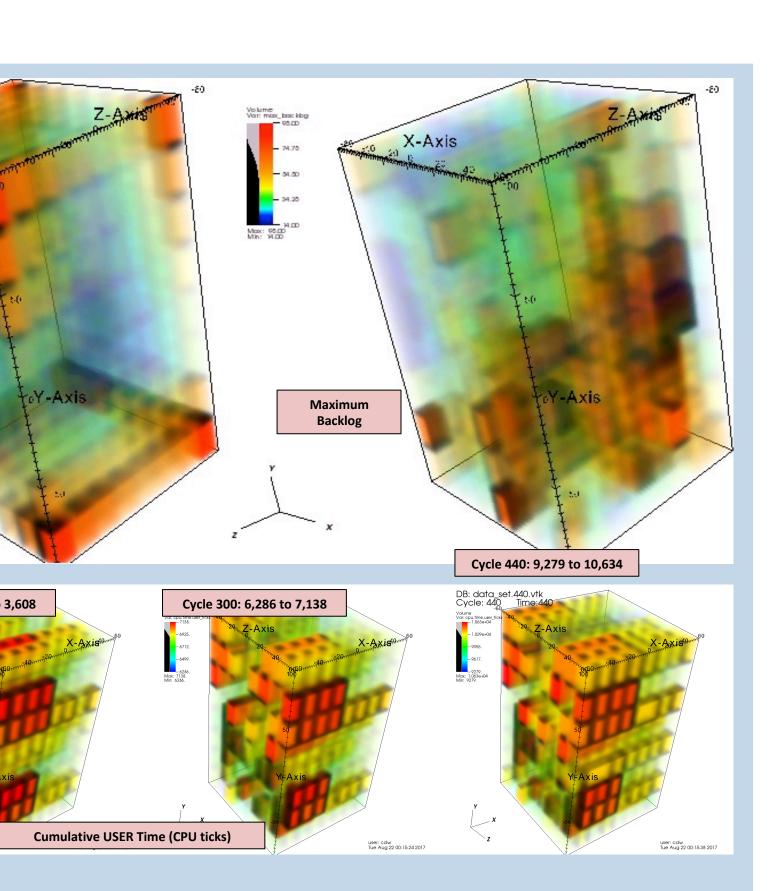
Results: Performance Understanding

over a curvilinear mesh.

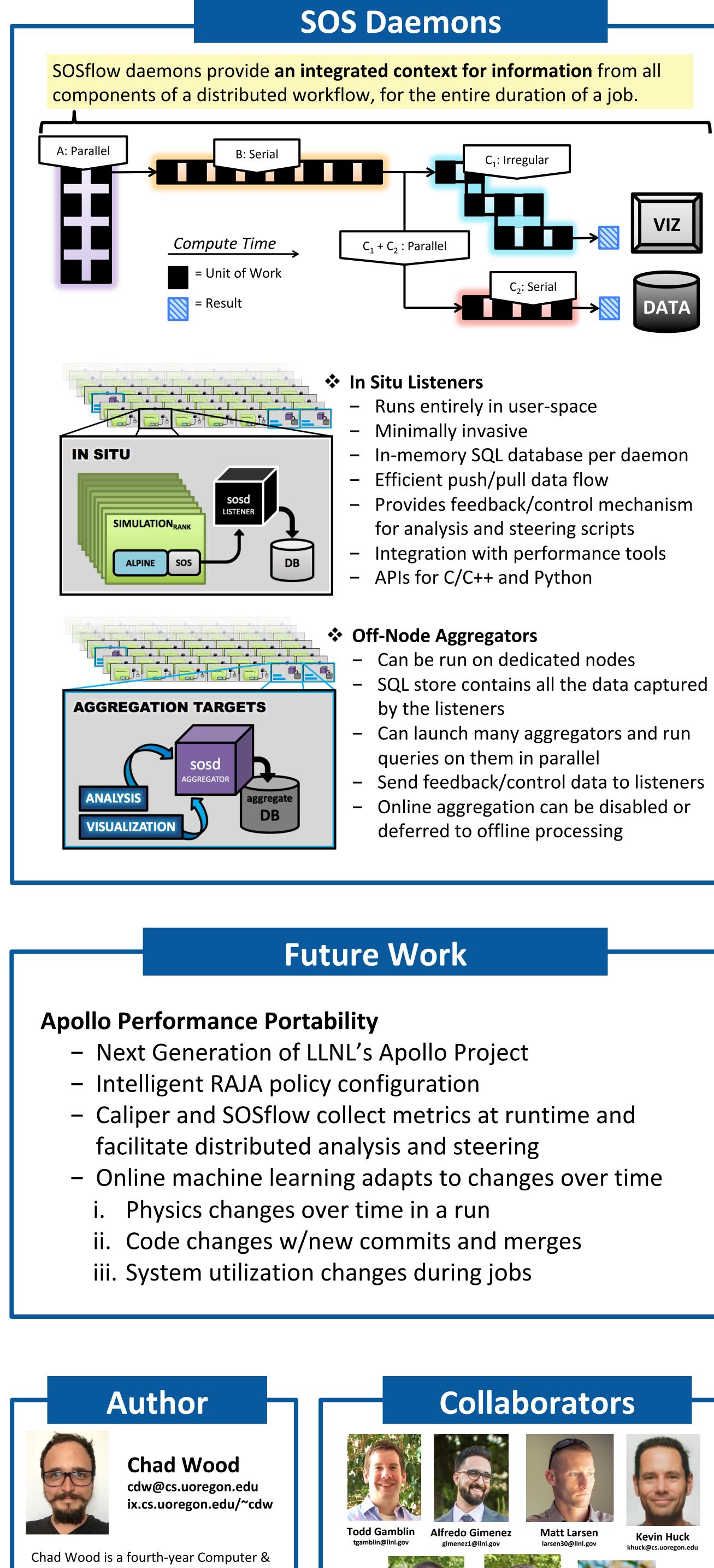


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✤No ad hoc instrumentation needed Updated geometry is automatically captured during the run to observe metrics projected over a changing mesh Anything published to SOSflow can be projected into these online views SOS runtime overhead within system noise Enable/disable without recompilation



Information Science PhD student at the University of Oregon. His research focus is on monitoring, introspection, feedback, and control for HPC systems, emphasizing online in situ operations and scalability.

