Algorithm Design for Large Scale Parallel FFT-Based Simulations on CPU-GPU Platforms Anuva Kulkarni, Franz Franchetti, Jelena Kovačević

Motivation

Extreme memory requirements and high communication overhead prevent scaling of large scale iterative simulations involving parallel FFTs to higher grid sizes, which is necessary for high resolution analysis.



An example is that of Moulinec Suquet's Basic Scheme to compute local stress and strain fields in materials, a partial differential equation simulation that uses FFTs



$$C_{ijkl}^0 u_{k,lj}(\mathbf{x}) + \tau_{ij,j}(\mathbf{x}) = 0$$

MSC Basic Scheme is solved by convolution with Green's function using FFT.

Increasing grid resolution is desirable. However, larger problem sizes must be run with parallelized code. This requires large parallel FFT computations which means high memory usage and all-all communication.



Memory requirement increases **32.4k** times!

Goal: Overcome these limitations and run stress-strain simulations for larger problem sizes

Our solution: An algorithm and software co-design for heterogeneous platforms using irregular domain decomposition and local FFTs.

Background

Algorithm 1 MSC Basic Scheme

- 1: Initialize: $\epsilon^0 \leftarrow E$.
- $\sigma_{mn}^0(\mathbf{x}) \leftarrow C_{mnkl}(\mathbf{x}) : \epsilon_{kl}^0(\mathbf{x})$
- 2: while $e_s > e_{tol}$ do
- $\hat{\sigma}_{mn}^{i}(\boldsymbol{\xi}) \leftarrow \text{FFT}(\sigma_{mn}^{i}(\mathbf{x}))$ Check convergence
- $\Delta \hat{\epsilon}_{kl}^{i+1}(\boldsymbol{\xi}) \leftarrow \hat{\Gamma}_{klmn}(\boldsymbol{\xi}) : \hat{\sigma}_{mn}^{i}(\boldsymbol{\xi})$
- Update strain: $\hat{\epsilon}_{kl}^{i+1}(\boldsymbol{\xi}) \leftarrow \hat{\epsilon}_{kl}^{i}(\boldsymbol{\xi}) \Delta \hat{\epsilon}_{kl}^{i+1}(\boldsymbol{\xi})$
- $\epsilon_{kl}^{i+1}(\mathbf{x}) \leftarrow \text{IFFT}(\hat{\epsilon}_{kl}^{i+1}(\boldsymbol{\xi}))$
- Update stress: $\sigma_{mn}^{i+1}(\mathbf{x}) \leftarrow C_{mnkl}(\mathbf{x}) : \epsilon_{kl}^{i+1}(\mathbf{x})$

Stress and strain fields in grain interiors are smooth. Hence we can treat these as separate domains.

99% energy of the space-domain Green's function is concentrated at central peak. Hence, Green's function can be truncated before convolution.

Right: N = 512 Slice of 3D component of space-domain Green's function



Original method

by Moulinec and Suquet

Proposed Method

The proposed MSC Alternate Scheme is a co-design of algorithm and software for heterogeneous platforms. It enables scaling of stress-strain simulations to large grids by overcoming high memory requirements and communication bottlenecks.



Smooth stress fields in grain interiors can be compactly represented with data models. This reduces communication overhead. Grain boundaries are convolved at full resolution without approximations.

Ideal model characteristics



Each grain (domain) is assigned to a GPU. For small grains, single GPU can process multiple grains. Distribution will be done using appropriate load balance. Local FFTs are performed on the GPU side.





20 40 60 80 100 120

100 120

20

40

60

80



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