

A Low-Communication Method to Solve Poisson's Equation on Locally-Structured Grids

Peter McCorquodale (PWMcCorquodale@lbl.gov), Phillip Colella (PColella@lbl.gov), Brian Van Straalen (BVStraalen@lbl.gov), Lawrence Berkeley National Laboratory; Christos Kavouklis (kavouklis1@llnl.gov), Lawrence Livermore National Laboratory



Continuous Problem and Solution

Poisson's equation arises in such fields as astrophysics, plasma physics, electrostatics, and fluid dynamics. We are solving it with infinite-domain boundary conditions:

$$\Delta\phi=f$$
 , $\phi(m{x})=-rac{1}{4\pi|m{x}|}\int f(m{y})dm{y}+o\left(rac{1}{|m{x}|}
ight)$ as $|m{x}| o\infty$

Solution of this equation, with Green's function, G:

$$\phi(\boldsymbol{x}) = (G * f)(\boldsymbol{x}) \equiv \int G(\boldsymbol{x} - \boldsymbol{y}) f(\boldsymbol{y}) d\boldsymbol{y} , G(\boldsymbol{z}) = -\frac{1}{4\pi |\boldsymbol{z}|}.$$

Method of Local Corrections (MLC)

Represent potential ϕ as linear superposition of small local discrete convolutions, with global coupling represented using a non-iterative form of geometric multigrid.

Communication cost like that of a *single* iteration of multigrid.

Computational kernels are multidimensional FFTs on small domains.

Local Discrete Convolutions

We can compute infinite-domain discrete Green's function G^h on any finite domain at any mesh resolution h. Compute $G^{h=1}$ once, store, and scale for any h.

$$(\Delta^{h=1}G^{h=1})[\boldsymbol{g}] = \begin{cases} 1, \text{if } \boldsymbol{g} = \boldsymbol{0}; \\ 0, \text{otherwise.} \end{cases} (G^h * f^h) = (\Delta^h)^{-1}(f^h)$$

$$(G''*f'')=(\Delta'')$$

fast convolution using 3D FFT

Scaling:
$$G^h[m{g}] = h^{-1}G^{h=1}[m{g}]$$
 $(G^h * f^h)[m{g}] \equiv \sum_{m{g}' \in \mathbb{Z}^3} h^3 G^h[m{g} - m{g}'] f^h[m{g}']$

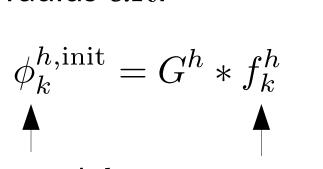
MLC Algorithm Description

Domain decomposition strategy:

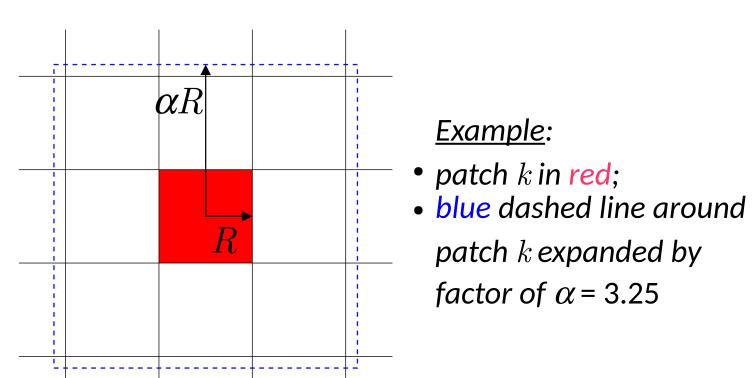
2 grid levels, fine (spacing h) and coarse (spacing H), with H/h = 4 fixed.

Decompose fine domain into fixed-sized patches with N grid points along each dimension; hence each patch has radius R = (N-1)h/2.

1. For each fine patch of radius R, compute local convolution on patch of radius αR :



expanded by factor α



patch k expanded by factor of α = 3.25 on patch kon patch k

2. Accumulate coarse-grid right-hand side by summing up localized contributions:

$$F^{H} = \sum_{i} \Delta^{H}(\text{Coarsen}(\phi_{k}^{h,\text{init}}))$$

- 3. Compute global coarse convolution: $\phi^H = G^H * F^H$
- 4. On each patch, solve a Dirichlet problem for Poisson, with face values

$$\phi_k^h = \sum_{k'} \phi_{k'}^{h, \text{init}} + \text{Interp}(\phi^H - \sum_{k'} \text{Coarsen}(\phi_{k'}^{h, \text{init}}))$$

Boundary values on the red face of patch k: contributions from $\phi_{k'}^{h, \text{init}}$ on dark blue regions, $\operatorname{Coarsen}(\phi_{k'}^{h,\operatorname{init}})$ interpolated from light by

For more than 2 levels, apply the above algorithm recursively.

High-Order Mehrstellen Stencils

A discrete Laplacian stencil of radius s has form $(\Delta^h \phi^h)_g = \sum a_s \phi_{g+s}^h$ and its truncation error looks like:

and its truncation error looks like:
$$\Delta^h \phi^h - \Delta \phi = C_2 h^2 \Delta(\Delta \phi) + \sum_{Q'=2}^{Q/2-1} h^{2Q'} \underbrace{\mathcal{L}^{2Q'}}_{\text{constant}} (\Delta \phi) + h^Q \underbrace{L^{Q+2}}_{\text{order } Q+2} (\phi) + O(h^{Q+2})$$
 stencil radius $s = \left| \frac{Q}{A} \right|$ linear differential operators

27-point operator: s = 1, Q = 6, $C_2 = 1/12$

117-point operator: s = 2, Q = 10, $C_2 = 1/12$

Modifying right-hand side of $\Delta \phi = f$ by adding appropriate derivatives of fgives a high-order approximation with compact stencil Δ^h .

(And for ϕ harmonic, truncation error is $O(h^Q)$ without modifying right-hand side.)

Solution Error

$$\phi^{\text{MLC}} - \phi = O(h^q) + ||f||_{\infty} O\left(\left(\frac{H}{\alpha Nh}\right)^Q\right)$$

From local truncation error, depends on local derivatives of ϕ and number of terms in Mehrstellen correction of right-hand side.

Typically q = 4 or 6.

Localization error, from representation of smooth nonlocal coupling

- no dependence on derivatives
- O(1) relative to h
- can adjust α , N, Q (stencil) as needed

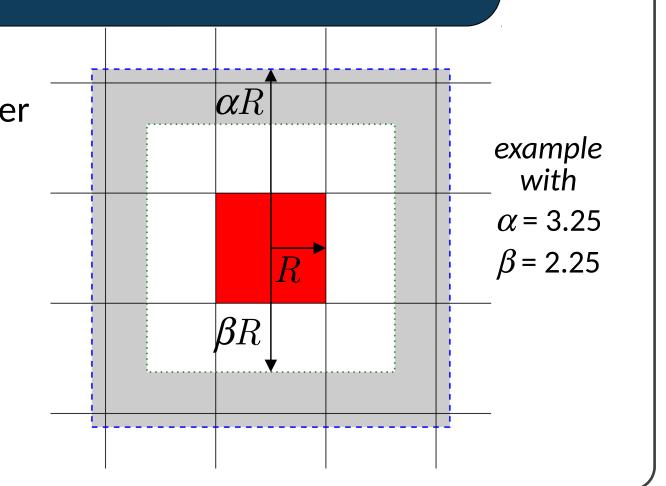
Modifying for Efficiency at Finest Level

At finest level only, reduce cost of computing local convolutions by replacing them on an outer annulus with fields induced by Legendre polynomial expansions of order P.

• Red + inner white (βR) region: $G^h * f^h$

• Gray ($\alpha R - \beta R$) region: $G^h * \operatorname{Proj}_{R}(f^h)$

Precompute convolutions of G^h with Legendre polynomials, and communicate only the coefficients for this region. Error is $O(h^{P+1})$.



Performance Analysis

Comparison with geometric multigrid (GMG) for 27-point Laplacian operator. GMG with 10 V-cycles, vs. MLC with q = 4, Q = 6, N = 33, $\alpha = 3.25$, $\beta = 2.25$, P = 3.

Algorithm	flops per gridpoint	loads (in bytes) per gridpoint	stores (in bytes) per gridpoint	messages per phase
GMG	1210	3840	1920	20
MLC	4637+398=5035	344	351	2
	step 1 everything else			

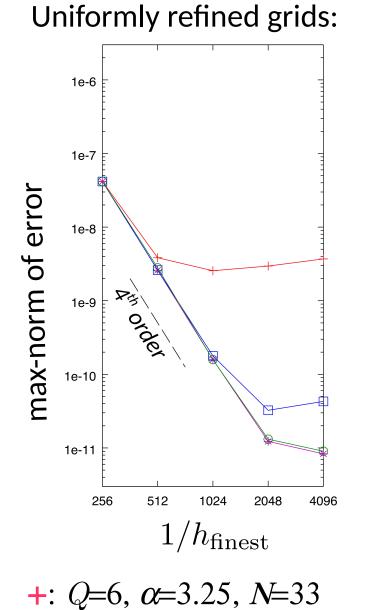
Acknowledgments

This research was supported at the Lawrence Berkeley National Laboratory by the Office of Advanced Scientific Computing Research

of the U.S. Department of Energy under Contract No. DE-AC02-05CH11231.

Accuracy Tests

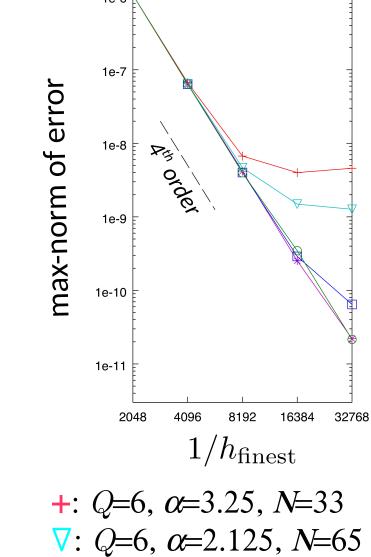
Use q = 4, patch size N either 33 or 65. We find error $O(h_{\text{finest}}^4)$ down to a barrier. Adaptively refined grids:



 \square : Q=6, α =3.25, N=65

★: *Q*=10, α=3.25, *N*=33

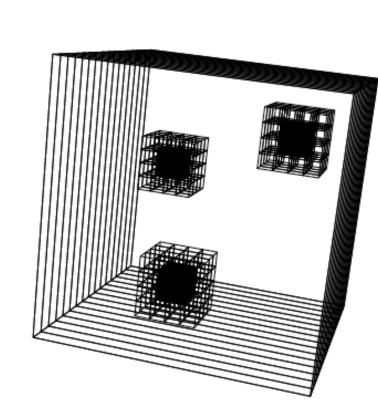
O: *Q*=10, α=3.25, *N*=65



 \square : Q=6, $\alpha=3.25$, N=65

★: *Q*=10, α=3.25, *N*=33

O: *Q*=10, α=3.25, *N*=65



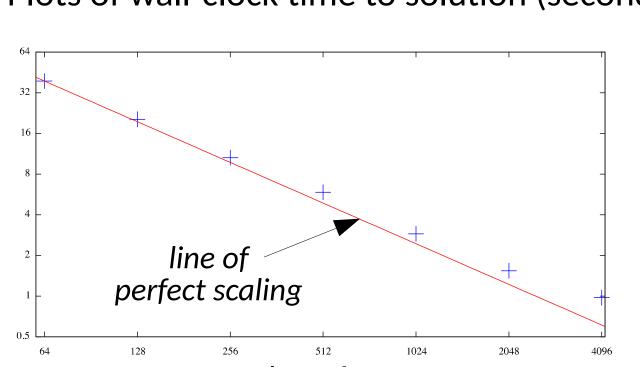
Above: Test case with 3 spherical charges, adaptively refined grids.

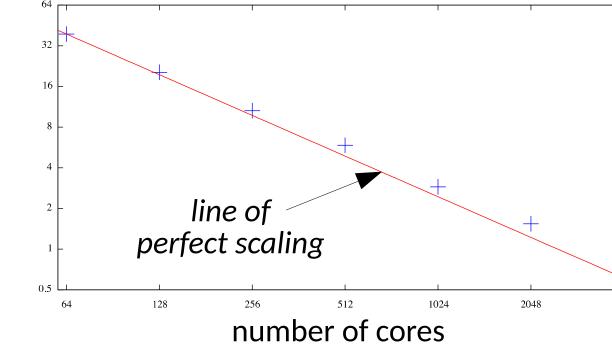
At finest level, project to Legendre polynomials of degree up to P = 3. α = 3.25 \Rightarrow β = 2.25; α = 2.125 \Rightarrow β = 1.625.

Scaling Tests

on NERSC Cori I (Haswell)

Numerical parameters: Q = 6, N = 33, α = 3.25, with finest level β = 2.25. Plots of wall-clock time to solution (seconds).

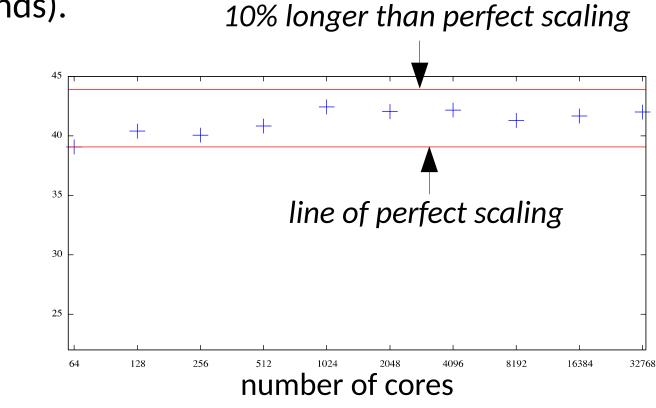




Strong scaling:

- fixed problem size with 10° grid points
- adaptive distribution
- (0.2% of domain refined at finest level) • over range 64 – 4K cores,
- strong scaling efficiency > 60%

• time to solution 39.1 \rightarrow .97 seconds



Replication weak scaling:

- adaptive base case with 10⁹ grid points
- replicated to obtain larger problems on 64 – 32K cores
- solution error independent of scale (~7 x 10⁻⁹)
- 92% weak scaling efficiency
- time to solution 39.1 42.4 seconds
- largest calculation has 5.1 x 10¹¹ unknowns, with equivalent uniform-grid resolution of $(64K)^3 = 2.8 \times 10^{14} \text{ unknowns.}$

Comparison with HPGMG

256 cores (8 nodes) on NERSC Cori I

- 6.1 sec for HPGMG with 10 V-cycles on uniform 1024³ grid (Sam Williams, private communication).
- 10.7 sec solve time for MLC on 10⁹ grid points adaptively distributed (with 0.2% of domain refined at finest level).

For More Information

- C. Kavouklis and P. Colella, "Computation of Volume Potentials on Structured Grids Using the Method of Local Corrections", submitted to Comm. App. Math. and Comp. Sci., also on http://arxiv.org/abs/1702.08111
- P. McCorquodale, P. Colella, G. T. Balls, and S. B. Baden, "A local corrections algorithm for solving Poisson's equation in three dimensions", Comm. App. Math. and Comp. Sci., 2:57—81 (2007).
- Our website http://www.chombo.lbl.gov